

From 3-valued semantics to supported model computation for logic programs in vector spaces

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(joint work with Chiaki Sakama and Katsumi Inoue)

Why supported models?

- Combinatorial problems:
 - SAT, TSP, planning, scheduling, bioinformatics....
 - Problem: to find a discrete finite solution satisfying constraints
- Solve by:
 - constraint programming (CP), integer linear programming (ILP), SAT, answer set programming (ASP),...
- ASP:
 - problem = logic program DB
 - solution = stable model of DB
 - BTW searching for supported models looks a good substitute
stable models \subseteq supported models

An overview

- Example program DB

$$\text{DB} = \{ \text{single}(X) \leftarrow \text{man}(X) \ \& \ \text{not}(\text{husband}(X)), \\ \text{husband}(X) \leftarrow \text{man}(X) \ \& \ \text{not}(\text{single}(X)) \}$$

$$\text{iff}(\text{DB}) = \{ s(X) \Leftrightarrow m(X) \ \& \ \text{not}(h(X)), \\ h(X) \Leftrightarrow m(X) \ \& \ \text{not}(s(X)) \}$$

\mathbf{M}_{DB} is a supported model iff $\mathbf{M}_{\text{DB}} \models \text{iff}(\text{DB})$

- Compute a supported model \mathbf{M}_{DB} by

Step 1: **Deterministically** compute three-valued model \mathbf{M}_{DB}^3

Step 2: Assign $\{\mathbf{t}, \mathbf{f}\}$ to undefined atoms in \mathbf{M}_{DB}^3 appropriately

– while conducting **Step 1** and **Step 2** in a **vector space**

by matrix operation for efficiency & scalability

Logic programming semantics in vector spaces: simple case

- DB is a Horn program:
 - taking a transitive closure r_2 of r_1

$$r_1(a,b), r_1(b,c),$$

$$r_2(X,Z) \leftarrow r_1(X,Z), r_2(X,Z) \leftarrow r_1(X,Y) \ \& \ r_2(Y,Z)$$
 - the least model $\mathbf{M}_{DB} = \{ a: \text{ground atom} \mid DB \vdash a \}$
- We embed the whole task in a vector space
 - $DB^g = \text{grounding of DB}$
 - encode DB^g by binary matrix \mathbf{Q} and threshold vector $\boldsymbol{\theta}$
 - represent \mathbf{M}_{DB} as binary vector \mathbf{u} (true(1),false(0))
 - compute \mathbf{u} s.t. $\mathbf{u} = (\mathbf{Q}\mathbf{u}) \geq \boldsymbol{\theta}$ where $(x) \geq \theta = (x \geq \theta ? 1 : 0)$

Computing matricized \mathbf{M}_{DB}

$$DB_1 = \{ p \leftarrow q \& r, q \leftarrow r \& s, r \leftarrow q \vee s, s \leftarrow \}$$

	p	q	r	s	θ	% threshold
$\mathbf{Q} =$ ↗ program matrix	0	1	1	0	2	% p: AND goal
	0	0	1	1	2	% q: AND goal
	0	1	0	1	1	% r: OR goal
	0	0	0	1	1	% s: fact as $s \leftarrow s$

$$\mathbf{u}_0 = [0 \quad 0 \quad 0 \quad 1]^T \quad \% \mathbf{u}_0(\text{fact})=1$$

$$\mathbf{u}_{n+1} = (\mathbf{Q}\mathbf{u}_n) \geq \theta \quad \% (x) \geq \theta = 1 \text{ if } x \geq \theta, = 0 \text{ o.w.}$$

$$\mathbf{u}_\infty = [1 \quad 1 \quad 1 \quad 1]^T \quad \% \text{ all atoms are true in } \mathbf{M}_{DB}$$

% $O(N^3)$ where $N = |\text{HB}|$

Hard case: computing supported models

- Supported models of DB with negation
 - may not exist
 - existence of supported model \rightarrow NP-complete
- Naïve strategy
 - non-deterministically assign $\{\mathbf{t}, \mathbf{f}\}$ to atoms to make a supported model

Our strategy

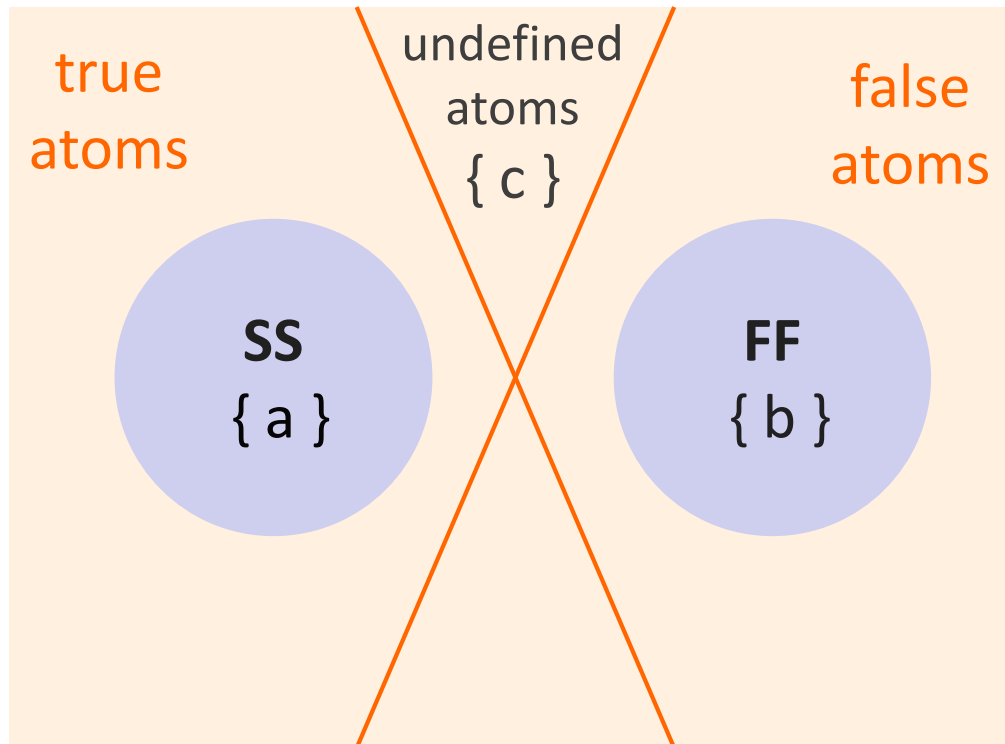
- $a \in \mathbf{SS}$ iff $\text{-}a$ succeeds by fair SLD refutation
 - a is true in all supported models of DB
- $a \in \mathbf{FF}$ iff $\text{-}a$ finitely fails by fair SLD refutation
 - a is false in all supported models of DB
- Search for supported models by
 - Step 1:** deterministically compute the least 3-valued model

$$\mathbf{M}_{DB}^3 = (\mathbf{SS}, \mathbf{FF}) \text{ by } \mathbf{DB}^d \text{ (dualized DB)}$$
 - remove nondeterminacy
 - Step 2:** non-deterministically assign $\{\mathbf{t}, \mathbf{f}\}$ to undefined atoms ($\notin \mathbf{SS} \cup \mathbf{FF}$) to make a supported model

Two supported models

DB:
 $a \leftarrow \text{not}(b)$
 $c \leftarrow a \ \& \ c$

iff(DB):
 $a \iff \text{not}(b)$
 $b \iff \text{false}$
 $c \iff a \ \& \ c$



SS
 $\text{:- } a \text{ succeeds}$
w.r.t. DB

FF
 $\text{:- } b \text{ finitely fails}$
w.r.t. DB

$\{a, \text{not}(b), c\} \models \text{iff}(\text{DB})$
 $\{a, \text{not}(b), \text{not}(c)\} \models \text{iff}(\text{DB}) \leftarrow \text{stable model}$

Computing SS and FF by DB^d in a vector space

DB:
 $a \leftarrow \text{not}(b)$
 $c \leftarrow a \ \& \ c$



DB^d :
 $a \leftarrow nb$
 $c \leftarrow a \ \& \ c$
 $na \leftarrow b$
 $nc \leftarrow na \vee nc$
 $nb \leftarrow$

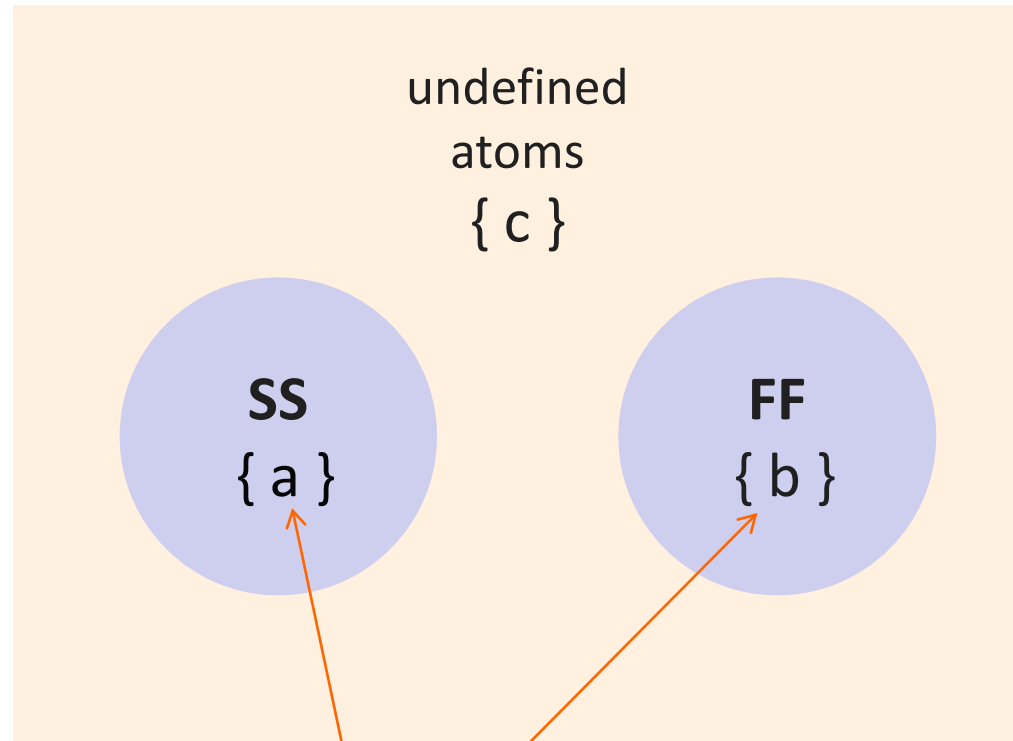


$$\mathbf{u}^d = (Q^d \mathbf{u}^d) \geq \theta$$



$$\mathbf{M}_{DB^d} = \{a, nb\}$$

$$DB^d \vdash a, nb$$



Compute all supported models of DB

Step-1:

Compute $\mathbf{u}^d_0, \mathbf{u}^d_1 \dots$ by $\mathbf{u}^d_i = (Q^d \mathbf{u}^d_{i-1}) \geq \theta$ and obtain the least fixed point $\mathbf{u}^d = (Q^d \mathbf{u}^d) \geq \theta$ of DB^d (or use (DG'84) algorithm)

Step-2:

Put $undef = \{ a \mid \mathbf{u}^d(a) = \mathbf{u}^d(na) = 0 \} = \text{undefined atoms}$ in \mathbf{M}_{DB}^3
Find possible assignments of truth values $\{\mathbf{t}(1), \mathbf{f}(0)\}$
to atoms in $undef$ s.t. the resulting interpretation $\mathbf{u} \models \text{iff}(DB)$

Experiment

- program DB: randomly generated 100 clause in $\{a_1, \dots, a_{100}\}$
- ini_determined_atom Δ_{ini} : $\text{fact}(\text{true}) \cup \text{no_callee_atom}(\text{false})$
- new_determined_atom Δ_{new} : $(\mathbf{SS} \cup \mathbf{FF}) \setminus \Delta_{ini}$ where $(\mathbf{SS}, \mathbf{FF}) = \mathbf{M}_{DB}^3$
- reduction_rate = $\#\Delta_{new} / 100$

ave. on 10 trials

base atoms $\{a_1, \dots, a_{10}\}$	used as fact $a \leftarrow$	used as tautology $a \leftarrow a$
$\#(\mathbf{SS} \cup \mathbf{FF})$	96.5	57.5
$\#\text{no_callee_atoms}$	3.6	12.4
$\#\Delta_{new}$	$96.5 - (3.6 + 10) = 83.9$	$57.5 - 12.4 = 45.1$
reduction_rate	83.9%	45.1%

83.9% of atoms are removed from search space by the introduction of **Step 1** that computes $(\mathbf{SS}, \mathbf{FF}) = \mathbf{M}_{DB}^3$

Conclusion

- We logically formulate combinatorial problems in such a way that a solution is a supported model of a logic program DB
- However computing supported models is NP-hard
- We proposed to reduce the search space by computing the **deterministic part (SS,FF)** separately in **Step 1** via DB^d in a **vector space**
- Our linear algebraic approach is particularly amenable to parallelism supported by GPU and many cores